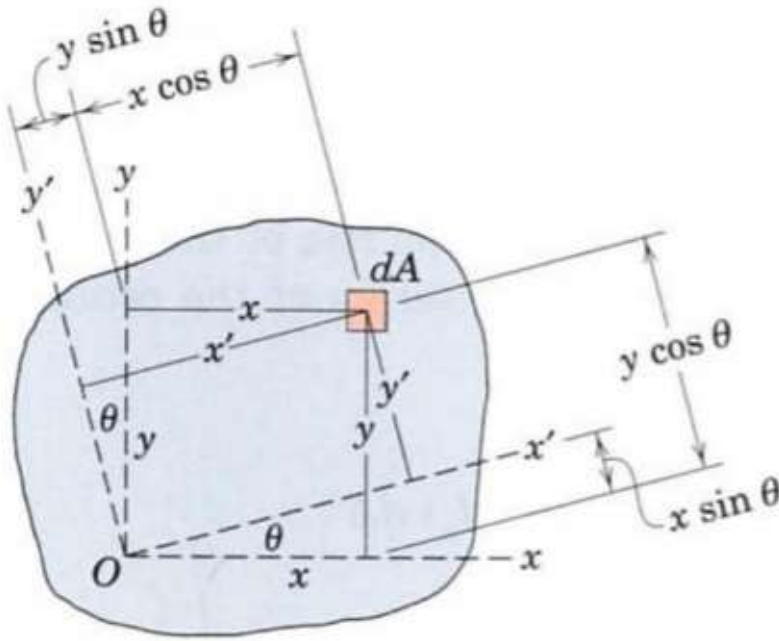


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## Rotação de inércia



Leis de transformação

Matriz de rotação:  $\begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix}$

$$x' := x \cdot \cos(\theta) + y \cdot \sin(\theta)$$

$$y' := y \cdot \cos(\theta) - x \cdot \sin(\theta)$$

$$I_{x'} := \int y'^2 dA \quad I_{y'} := \int x'^2 dA \quad I_{x'y'} := \int (x' \cdot y') dA$$

$$dI_{x'} := y'^2 \cdot dA \quad dI_{y'} := x'^2 \cdot dA \quad dI_{x'y'} := x' \cdot y' \cdot dA$$

$$dI_{x'} := (y \cdot \cos(\theta) - x \cdot \sin(\theta))^2 \cdot dA$$

$$dI_{x'} := (y \cdot \cos(\theta) + x \cdot \sin(\theta))^2 \cdot dA$$

$$dI_{x'y'} := (y \cdot \cos(\theta) - x \cdot \sin(\theta)) \cdot (y \cdot \cos(\theta) + x \cdot \sin(\theta)) \cdot dA$$

$$dI_{x'} := \left( (y \cdot \cos(\theta))^2 - 2 \cdot y \cdot \cos(\theta) \cdot x \cdot \sin(\theta) + (x \cdot \sin(\theta))^2 \right) \cdot dA$$

$$dI_{y'} := \left( (y \cdot \cos(\theta))^2 + 2 \cdot y \cdot \cos(\theta) \cdot x \cdot \sin(\theta) + (x \cdot \sin(\theta))^2 \right) \cdot dA$$

$$dI_{x'y'} := (y \cdot \cos(\theta))^2 + (x \cdot \sin(\theta))^2$$

Sabendo que:

$$\cos(x)^2 := \frac{1}{2} \cdot (1 + \cos(2 \cdot x))$$

$$\sin(x)^2 := \frac{1}{2} \cdot (1 - \cos(2 \cdot x))$$

$$\sin(2 \cdot x) := 2 \cdot \sin(x) \cdot \cos(x)$$

Substituindo e integrando novamente, teremos:

$$I_{x'} := I_x \cdot \cos(\theta)^2 + I_y \cdot \sin(\theta)^2 - 2 \cdot I_{xy} \cdot \sin(\theta) \cdot \cos(\theta)$$

$$I_{y'} := I_x \cdot \sin(\theta)^2 + I_y \cdot \cos(\theta)^2 + 2 \cdot I_{xy} \cdot \sin(\theta) \cdot \cos(\theta)$$

$$I_{x'y'} := I_x \cdot \sin(\theta) \cdot \cos(\theta) - I_y \cdot \sin(\theta) \cdot \cos(\theta) + I_{xy} \cdot (\cos(\theta)^2 - \sin(\theta)^2)$$